

DSC 190

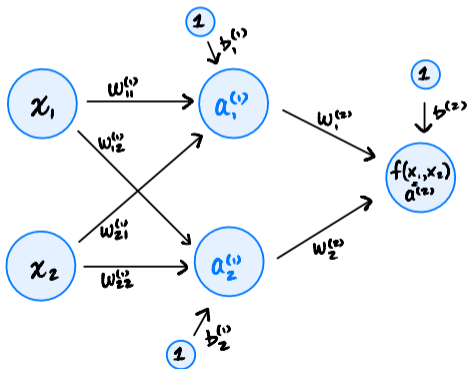
Machine Learning: Representations

Lecture 13 | Part 1

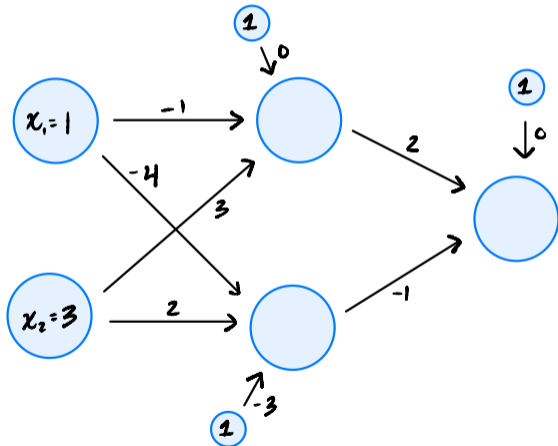
Convexity in 1-d

Neural Networks

A NN is just a function: $f(\vec{x}; \vec{w})$



Example



Learning

- ▶ **Given:** a data set $(\vec{x}^{(i)}, y_i)$
- ▶ **Find:** weights \vec{w} minimizing some cost function (e.g., expected square loss):

$$C(\vec{w}) = \frac{1}{n} \sum_{i=1}^n (f(\vec{x}^{(i)}; \vec{w}) - y_i)^2$$

- ▶ **Problem:** there is no closed-form solution

Gradient Descent

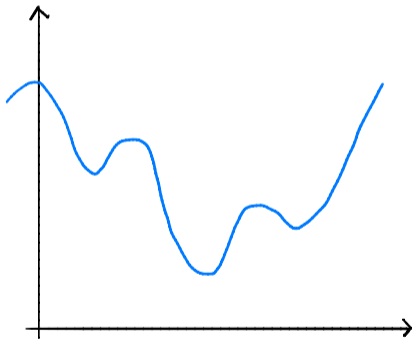
- ▶ **Idea:** start at arbitrary $\vec{w}^{(0)}$, walk in direction of gradient:

$$\nabla C = \begin{pmatrix} \frac{\partial C}{\partial w_0} \\ \frac{\partial C}{\partial w_1} \\ \vdots \\ \frac{\partial C}{\partial w_k} \end{pmatrix}$$

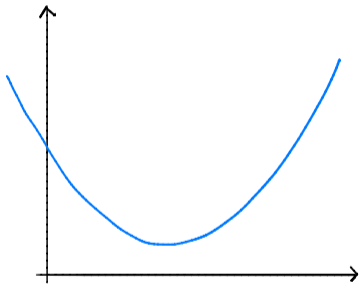
Question

When is gradient descent guaranteed to work?

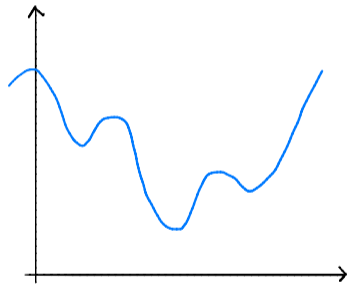
Not here...



Convex Functions



Convex



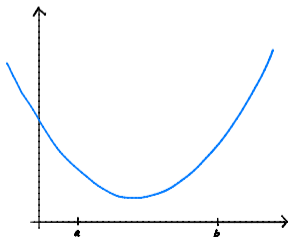
Non-convex

Convexity: Definition

- ▶ f is **convex** if for **every** a, b the line segment between

$$(a, f(a)) \quad \text{and} \quad (b, f(b))$$

does not go below the plot of f .

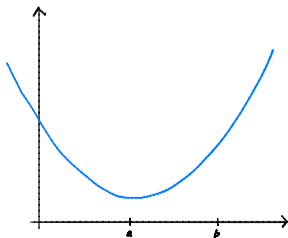


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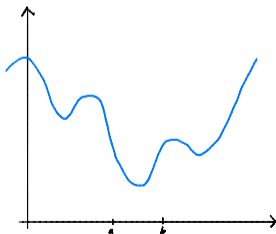


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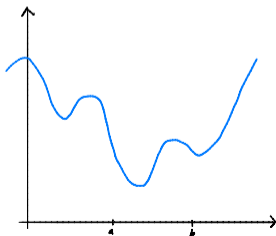


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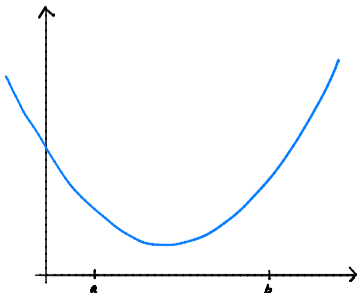
Other Terms

- ▶ If a function is not convex, it is **non-convex**.
- ▶ **Strictly convex**: the line lies strictly above curve.
- ▶ **Concave**: the line lies on or below curve.

Convexity: Formal Definition

- ▶ A function $f : \mathbb{R} \rightarrow \mathbb{R}$ is **convex** if for every choice of $a, b \in \mathbb{R}$ and $t \in [0, 1]$:

$$(1 - t)f(a) + tf(b) \geq f((1 - t)a + tb).$$

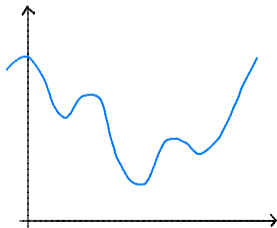
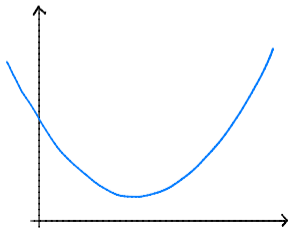


Example

Is $f(x) = |x|$ convex?

Another View: Second Derivatives

- ▶ If $\frac{d^2f}{dx^2}(x) \geq 0$ for all x , then f is convex.
- ▶ Example: $f(x) = x^4$ is convex.
- ▶ **Warning!** Only works if f is twice differentiable!



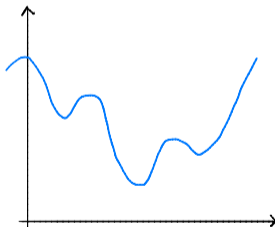
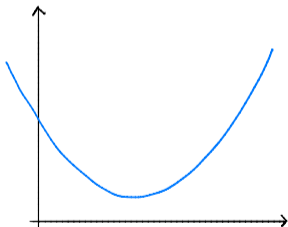
Another View: Second Derivatives

- ▶ “Best” straight line at x_0 :
 - ▶ $h_1(z) = f'(x_0) \cdot z + b$

- ▶ “Best” parabola at x_0 :
 - ▶ At x_0 , f looks like $h_2(z) = \frac{1}{2}f''(x_0) \cdot z^2 + f'(x_0)z + c$
 - ▶ Possibilities: upward-facing, downward-facing.

Convexity and Parabolas

- ▶ Convex if for **every** x_0 , parabola is upward-facing.
 - ▶ That is, $f''(x_0) \geq 0$.



Convexity and Gradient Descent

- ▶ Convex functions are (relatively) easy to optimize.
- ▶ **Theorem:** if $R(x)$ is convex and differentiable¹² then gradient descent converges to a **global optimum** of R *provided* that the step size is small enough³.

¹and its derivative is not too wild

²actually, a modified GD works on non-differentiable functions

³step size related to steepness.

Nonconvexity and Gradient Descent

- ▶ Nonconvex functions are (relatively) hard to optimize.
- ▶ Gradient descent can still be useful.
- ▶ But not guaranteed to converge to a global minimum.

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Machine Learning: Representations

Lecture 13 | Part 2

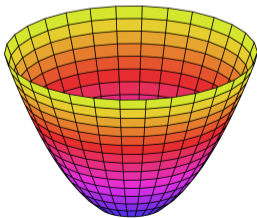
Convexity in Many Dimensions

Convexity: Definition

- ▶ $f(\vec{x})$ is **convex** if for **every** \vec{a}, \vec{b} the line segment between

$$(\vec{a}, f(\vec{a})) \quad \text{and} \quad (\vec{b}, f(\vec{b}))$$

does not go below the plot of f .



Convexity: Formal Definition

- ▶ A function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is **convex** if for every choice of $\vec{a}, \vec{b} \in \mathbb{R}^d$ and $t \in [0, 1]$:

$$(1 - t)f(\vec{a}) + tf(\vec{b}) \geq f((1 - t)\vec{a} + t\vec{b}).$$

The Second Derivative Test

- ▶ For 1-d functions, convex if second derivative ≥ 0 .
- ▶ For 2-d functions, convex if ???

The Hessian Matrix

- ▶ Create the **Hessian** matrix of second derivatives:

$$H(\vec{X}) = \begin{pmatrix} \frac{\partial f^2}{\partial x_1^2}(\vec{X}) & \frac{\partial f^2}{\partial x_1 x_2}(\vec{X}) \\ \frac{\partial f^2}{\partial x_2 x_1}(\vec{X}) & \frac{\partial f^2}{\partial x_2^2}(\vec{X}) \end{pmatrix}$$

In General

- If $f : \mathbb{R}^d \rightarrow \mathbb{R}$, the **Hessian** at \vec{x} is:

$$H(\vec{x}) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2}(\vec{x}) & \frac{\partial^2 f}{\partial x_1 \partial x_2}(\vec{x}) & \dots & \frac{\partial^2 f}{\partial x_1 \partial x_d}(\vec{x}) \\ \frac{\partial^2 f}{\partial x_2 \partial x_1}(\vec{x}) & \frac{\partial^2 f}{\partial x_2^2}(\vec{x}) & \dots & \frac{\partial^2 f}{\partial x_2 \partial x_d}(\vec{x}) \\ \dots & \dots & \dots & \dots \\ \frac{\partial^2 f}{\partial x_d \partial x_1}(\vec{x}) & \frac{\partial^2 f}{\partial x_d^2}(\vec{x}) & \dots & \frac{\partial^2 f}{\partial x_d^2}(\vec{x}) \end{pmatrix}$$

The Second Derivative Test

- ▶ A function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ is **convex** if for any $\vec{x} \in \mathbb{R}^d$, the Hessian matrix $H(\vec{x})$ is **positive semi-definite**.
- ▶ That is, all eigenvalues are ≥ 0